



Working Together for a Greener Society

Future of Power Electronics and the Earth

High Efficiency and High Performance, Sinusoidal Motor Driver IC SX6812xM Series



SX6812xM Series Selection Guide



Part Number	V _{DSS}	۱ _D	R _{DS(ON)}	Rotation Pulse Signal	Status
SX68128MA		1.5 A	3.6 Ω (max.)	3 ppr	Preview
SX68128MB	600 V	1.5 A	3.6 Ω (max.)	2.4 ppr	Active
SX68127MA		2.0 A	2.5 Ω (max.)	3 ppr	Preview

Recommended Applications

- Air Conditioner Indoor Fan Motor
- Air Purifier Fan Motor

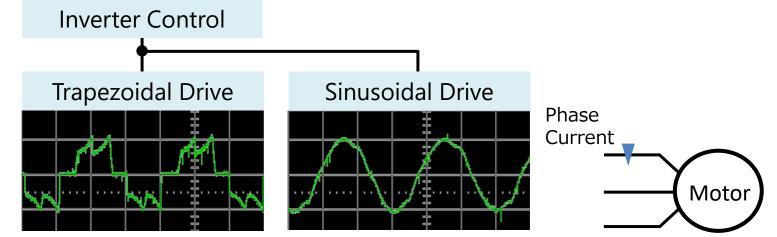




Drive Method

Drive Method

Motor drive methods include trapezoidal and sinusoidal.



Features

The following table shows the drive methods and the features.

The SX6812xM series use the sinusoidal drive that provides the high efficiency and low audible noise.

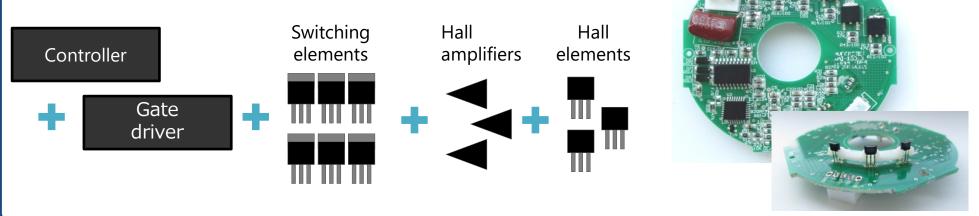
Drive Method	Parameter				
Drive Method	Motor Efficiency	Switching Efficiency	Quietness	Torque Ripple	
Trapezoidal	High	Higher	Quiet	Large	
Sinusoidal	Higher	High	Quieter	Small	

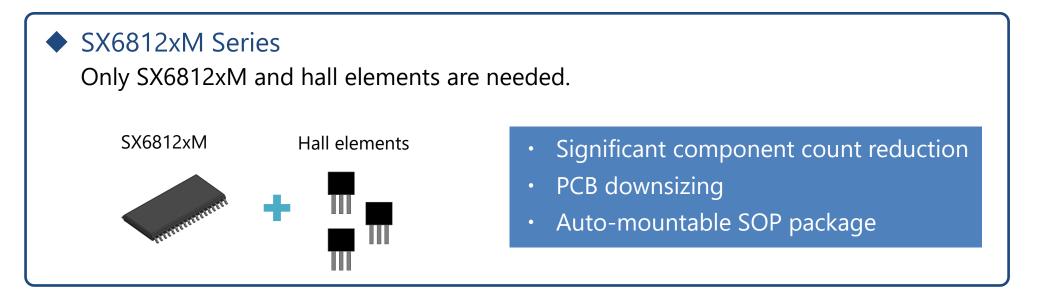
Downsizing



• Existing Motor Drivers

Many discrete elements are needed.



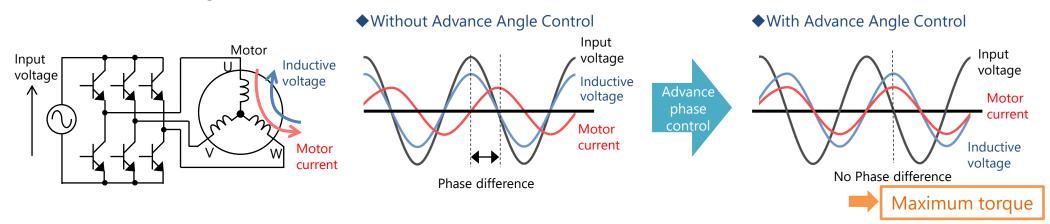


Advance Angle Control



The phase of the current flowing through the motor is delayed from the phase of the inductive voltage due to the influence of the inductance of the winding.

The SX6812xM series have the advance angle control function that reduces the phase difference between the inductive voltage and the motor current. As a result, the motor can be used with the maximum torque.



In the SX6812xM series, the phase of the inductive voltage can be adjusted by the LA pin voltage.

◆ LA Pin Peripheral Circuit ◆ LA Pin Voltage–Advance Angle Characteristic Example of Advance Angle Setting 60 5 Advance Angle (°) VSP V_{LA}, V_{VSP} (V) 4 R1 40 \geq VZ C_{LA} 3 ΙΔ 2 20 R2 \geq 0 COM 0 3 0 2 4 5 0 $V_{LA}(V)$

 $R1 = R2, V_7 = 1.5 V$ V_{VSP} V_{IA} 2 3 5 4 $V_{SP}(V)$

Protections



The SX6812xM series have built-in motor control parts, and can simultaneously monitor the drive signal and the motor driver state. In addition to the existing protections, the ICs also have the protections such as the locked motor protection, the inverse rotation detection, and the hall signal fault detection. Improving the performance of the ICs reduce the number of external components. This provides reducing the system size and the designing resources, and improving the system reliability.

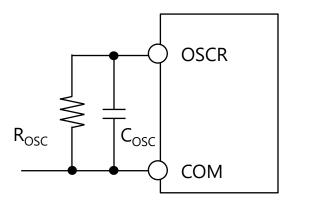
Protection	Description
Undervoltage Lockout for Power Supply (UVLO)	Prevents the critical damage caused by increased loss of the power elements. Integrated into the VB and VCC pins.
Thermal Shutdown (TSD)	Detects the temperature of the monolithic IC, T _j . When T _j \geq 130 °C, all switching elements are turned off. Then, when T _j \leq 90 °C or lower, the IC returns to the normal operation.
Overcurrent Limiting Function (OCL)	When the motor current reaches the setting value or more, the high-side switching elements are turned off by pulse-by-pulse.
Overcurrent Protection (OCP)	When the motor current reaches the setting value or more, all switching elements are turned off. The IC restarts automatically after the OCP hold time of 15 ms.
Locked Motor Protection	If the position information of the hall elements does not change for more than 6 seconds, all switching elements are turned off for 35 seconds.
Inverse Rotation Detection	If the rotation direction of the actual motor does not match that of the setting direction, the drive method becomes trapezoidal.
Hall Signal Fault Detection	If the position detection signals of three hall elements are "H, H, H" or "L, L, L", all switching elements are turned off.

Adjustment of Carrier Frequency

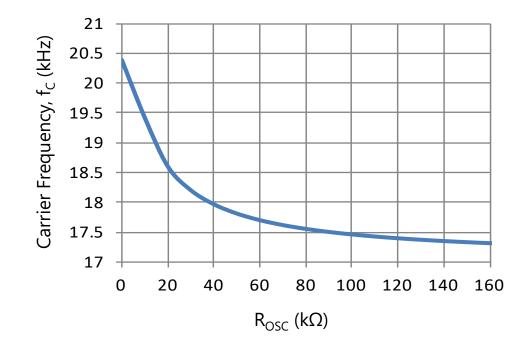


A carrier frequency is adjusted by R_{OSC} connected to the OSCR pin.

• OSCR Pin Peripheral Circuit



Relationship of Carrier Frequency and Resistance Value



Adjustable Range of Carrier Frequency

R _{OSC} (kΩ)	Carrier Frequency, f _C (kHz)		
Short	20.4		
Open	17.0		

Switching of Speed Control and Drive Method



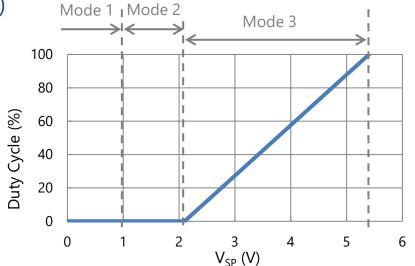
The SX6812xM series switches a drive method according to a frequency. The motor speed is detected by the VSP pin, and then the operation mode is switched according to the VSP pin voltage. This realizes a stable startup operation.

Switching of Drive Method

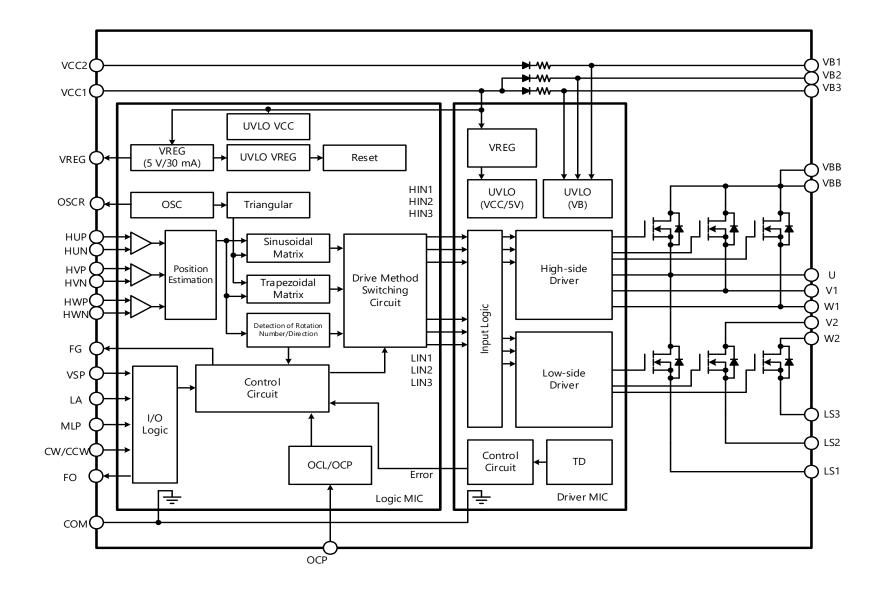
	Frequency	Drive Method
	Less than 1 Hz	Trapezoidal
More than 1 Hz Sinusoidal two-phase modulation		Sinusoidal two-phase modulation

Switching of Operation Mode (see the right graph)

Mode	VSP Pin Voltage	Operation		
1	0.0 V to 1.0 V	All switching elements are turned off		
2	1.0 V to 2.1 V	Boot capacitor is charged (low-side switching elements are turned on)		
3 2.1 V to 5.4 V		PWM modulation		

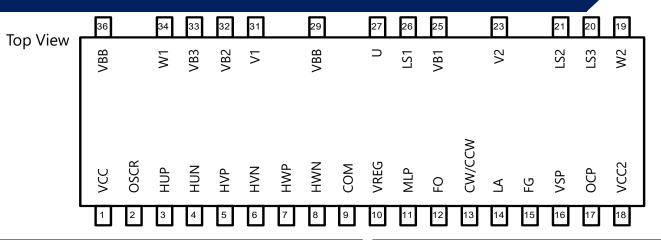






Pin Assignment

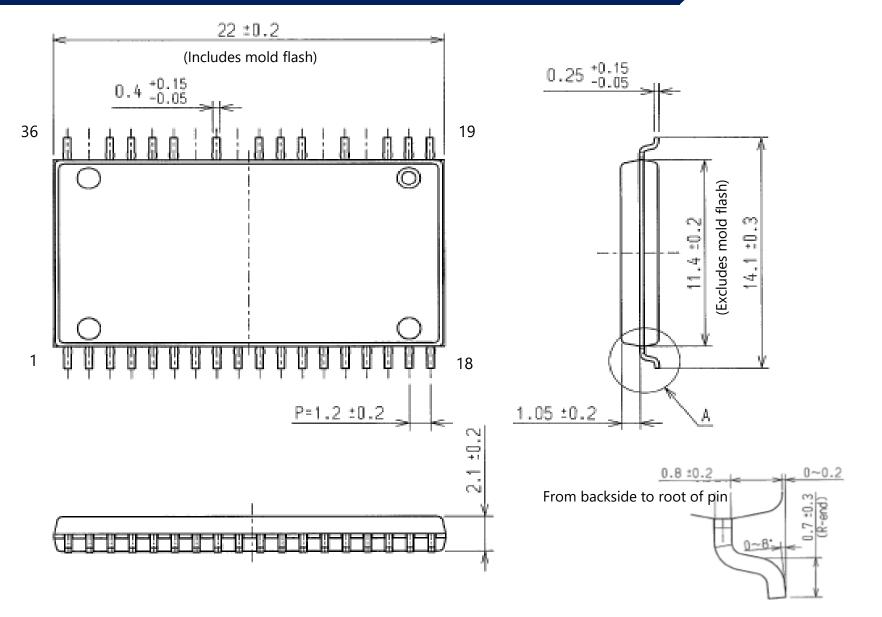




Number	Name	Description	Number	Name	Description
1	VCC1	Logic supply voltage input	19	W2	W-phase output (connected to W1 externally)
2	OSCR	Switching frequency adjustment input	20	LS3	Low-side source 3 (connected to LS1, LS2 externally)
3	HUP	U-phase hall element input (+)	21	LS2	Low-side source 2 (connected to LS1, LS3 externally)
4	HUN	U-phase hall element input (–)	22		Pin removed
5	HVP	V-phase hall element input (+)	23	V2	V-phase output (connected to V1 externally)
6	HVN	V-phase hall element input (–)	24		Pin removed
7	HWP	W-phase hall element input (+)	25	VB1	U-phase high-side floating supply voltage input
8	HWN	W-phase hall element input (-)	26	LS1	Low-side source 1 (connected to LS2, LS3 externally)
9	СОМ	Logic ground	27	U	U-phase output
10	VREG	Built-in regulator output	28		Pin removed
11	MLP	Locked motor protection setting input	29	VBB	Main power supply
12	FO	Fault signal output	30		Pin removed
13	CW/CCW	Rotation direction switching setting input	31	V1	V-phase output (connected to V2 externally)
14	LA	Advance angle and drive method setting input	32	VB2	V-phase high-side floating supply voltage input
15	FG	Position signal output	33	VB3	W-phase high-side floating supply voltage input
16	VSP	Speed control command input	34	W1	W-phase output (connected to W2 externally)
17	OCP	Overcurrent detection signal input	35		Pin removed
18	VCC2	Logic supply voltage input	36	VBB	Main power supply

Physical Dimension (SOP36)





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Summary

The Sinusoidal SX6812xM series provide a motor with high efficiency, quietness, and low noise. The compact SOP package includes a control circuit, drive circuit, and various protections. The high performance of the ICs realize not only the system downsizing but also the improvement of the system reliability.



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